

### DEVELOPMENT AND OPTIMIZATION OF AN ELECTRIC HYPERCAR POWERTRAIN

Gerhard Vosloo, Rimac Automobili d.o.o. IPG Apply & Innovate 2020

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2020

AGENDA

- Introduction
- Background and motivation
- Development process
- Targets
- Use case: longitudinal performance
- Use case: track performance
- Use case: range and efficiency
- Correlation and validation

### WHO WE ARE

#### 31M7C

- Founded: 2009 (first employees in April 2011)
- Team today: 700+ people (400+ in R&D)
- Completed B2B projects: 30+
- Developed, produced and delivered world's fastest electric supercar
- Tier 1 supplier to 10 Global OEMs
- Total investment so far: ~€140M
- Deloitte technology fast 50: 10<sup>th</sup> place 4 consecutive years amongst top 100

- Rimac Automobili is

Croatia

**PO** 

- Mate Rimac converts his

electric race car and the

BMW E30 into an

idea is born

2008

founded in Sveta Nedelja,

10

- Mate Rimac breaks 5

Guinness and FIA World

accelerating electric car.

records for the fastest

11

- Awarded as the best employer in Croatia
- European Business Award



### **OEM PROJECTS**

Development of an powertrain system and electronics of Automobili Pininfarina Battista electric hypercar.



Development of an electric version of Hyundai Motor's N brand midship sports car and a high-performance fuel cell electric vehicle.



Development and production of the Aston Martin Red Bull Valkyrie supercar hybrid battery system, infotainment and connectivity system



Development of full EV system for CUPRA (SEAT) e-racer prototype



**K**oenigsegg

Development and manufacturing batteries and power distribution units for the Koenigsegg Regera hypercar.





Developed an electric version of the iconic Jaguar E-Type, which was used as the groom and bride car for the Meghan Markle and Prince Harry's royal wedding.

ΙΜΛΟ

# **HYPERCARS**

# TECHNOLOGY

A new approach to high performance through technology and innovation

Technology developed from the ground up, driving the electric revolution

### HYPERCAR | CONCEPT\_ORE

ZIMAC

#### **2.5** sec **14** sec **1224** hp 355 km/h 1600 Nm 350 km

0-100km/h

0-300km/h 900 kW Electrically limited

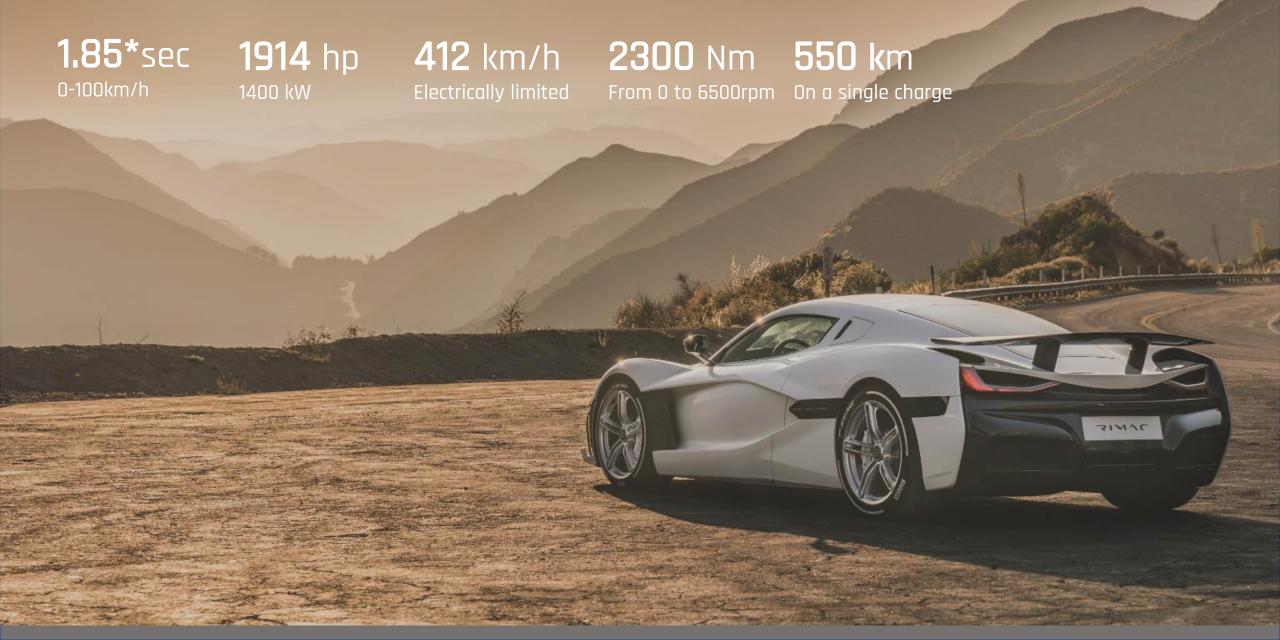
From 0 to 6500rpm On a single charge



Debuted at the 2011 Frankfurt International Auto Show



#### RIMAC



### C\_TWO

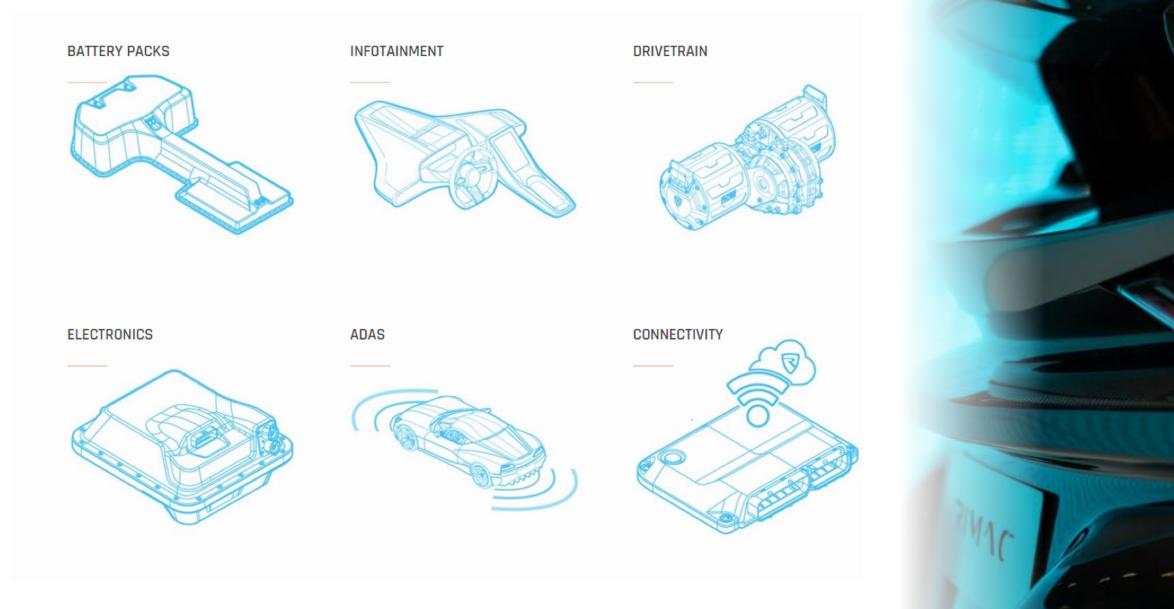
- Globally homologated
- 4 independently controlled electric motors power each wheel
- Rimac all-wheel torque vectoring
- Full carbon fibre monocoque with structurally integrated battery pack
- Active Aerodynamics
- Autonomous driving capabilities
- Driving Coach







### **OUR SERVICES**

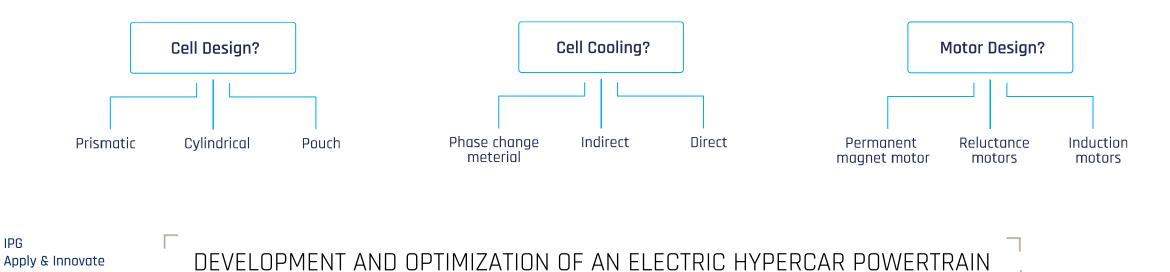


### **BACKGROUND & MOTIVATION**

- Hypercar EV segment \_
  - Low volume
  - Less cost conscious —
  - Incorporates latest and most advanced EV technology
- Electric vehicles (EV) are undergoing exponential growth and development
  - Electric motors \_
  - Inverters \_
  - **Battery Cells** —
  - Battery pack design and cooling \_
  - Architecture \_

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### THE CHALLENGE FOR EV HYPERCARS

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Rapid prototyping and flexibility to adapt and include latest EV technology ... or risk being left behind by competitors!

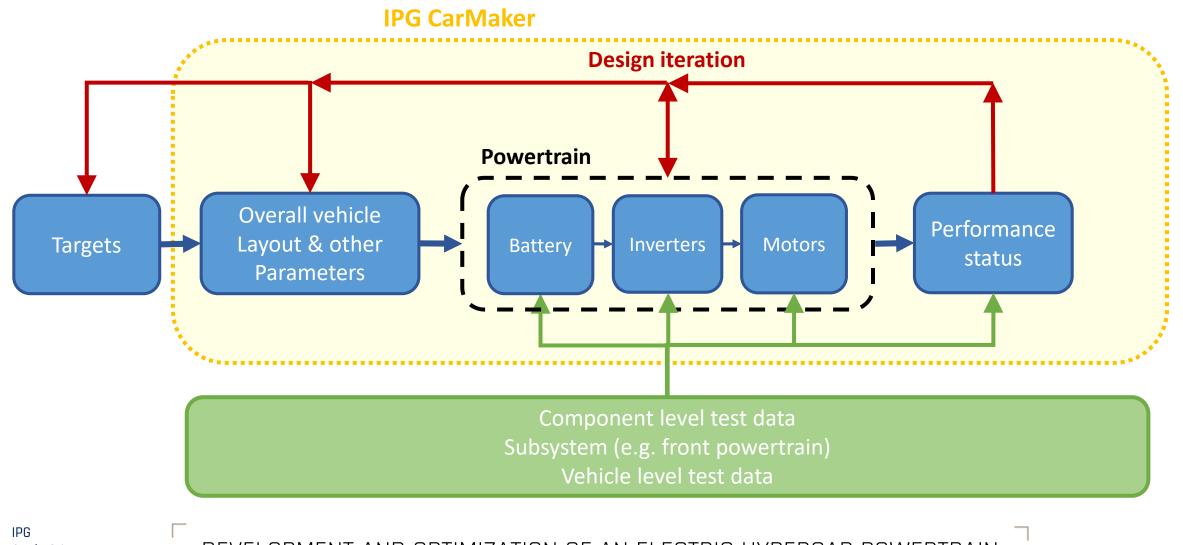
"If you aren't first you're last" – Ricky Bobby

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### THE DEVELOPMENT PROCESS





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### **TARGETS\***

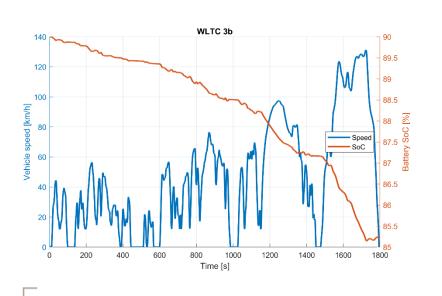
\*Targets listed does not represent actual targets of the Rimac C\_Two

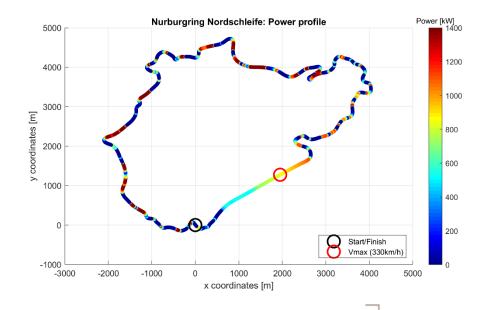
- Performance:
  - Longitudinal
    e.g. 10 x 0-100-0 km/h without overheating/de-rating

#### – Track

e.g. 1 lap of Nürburgring, Nordschleife without any power de-rating

– Range: e.g. 550+km on WLTP





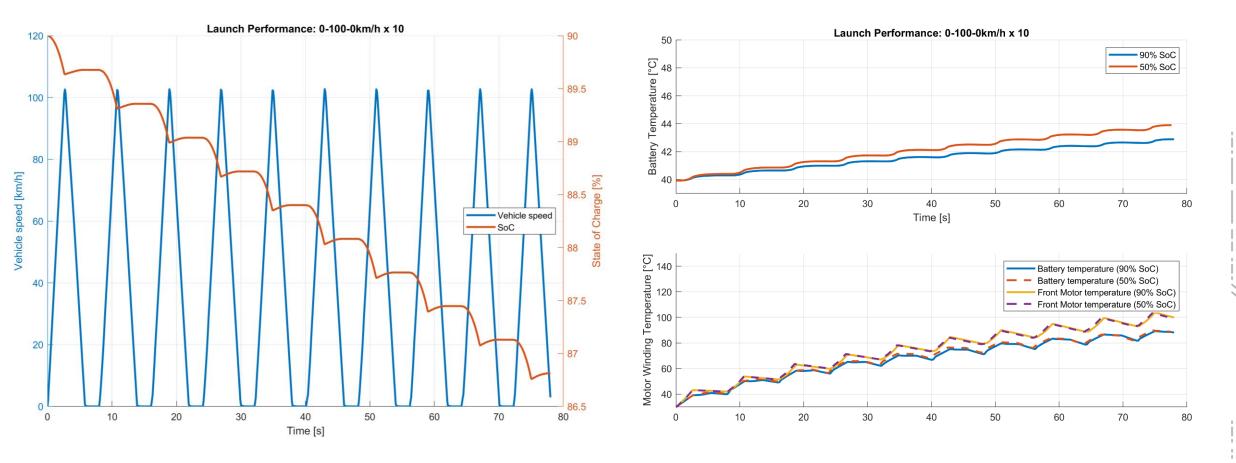
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#### **JVVIS**

### LONGITUDINAL PERFORMANCE

#### Performance analysis at lower SoC



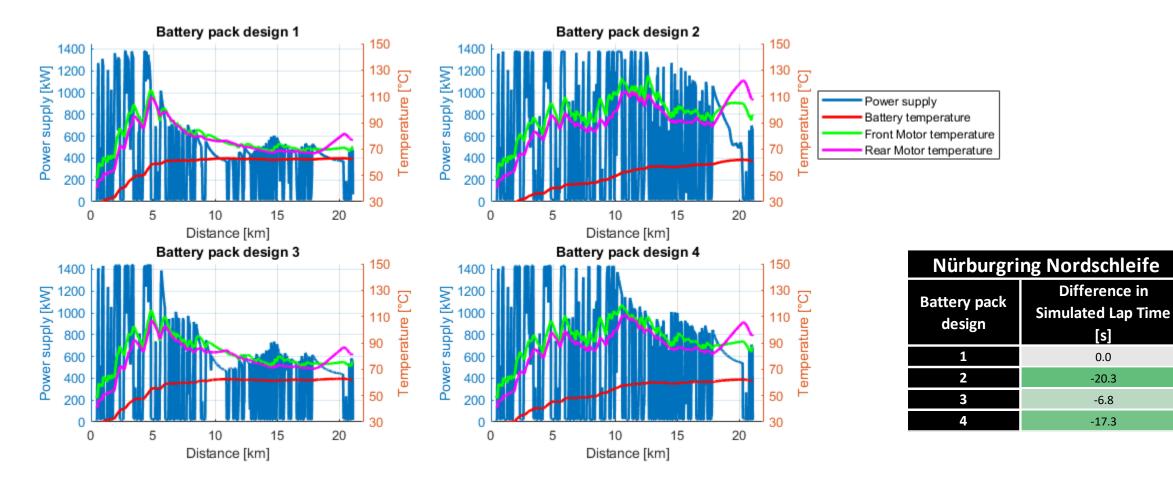
NOTE: Results are given as an example, data is not representative of current, nor previous status

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## TRACK PERFORMANCE ANALYSIS: Nürburgring Nordschleife

Performance comparison of different battery pack designs

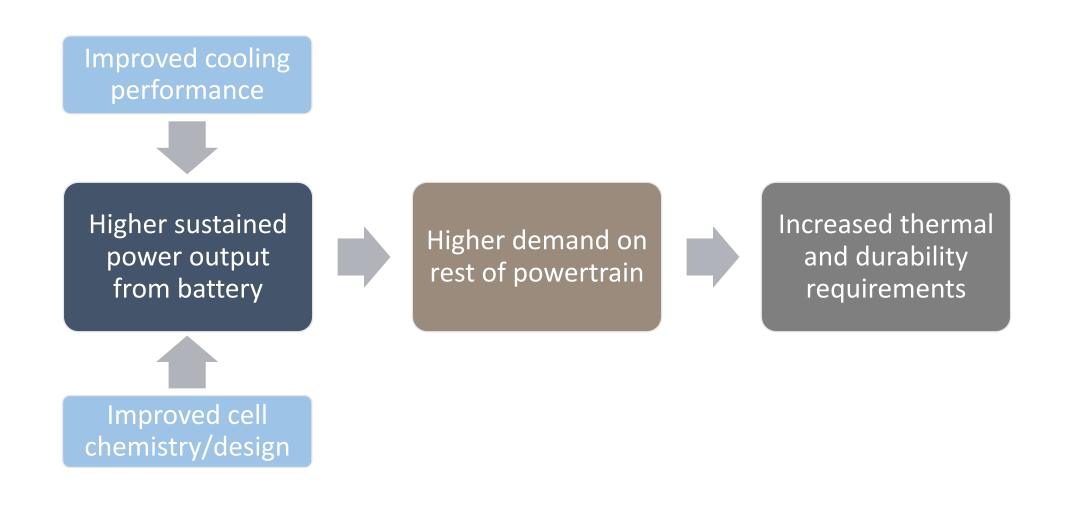


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### **ELIMINATE BOTTLENECKS FOR A HOLISTIC DESIGN**



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### RANGE AND EFFICIENCY ON WLTC CYCLE

#### Consumption and identifying losses

WLTC consumption, range and losses				
Consumption			XXX.X Wh/km	
Range			XXX.X km	
ontribution of Losses	Aerodynamic Losses		23.4%	
	Powertrain Losses	Battery	1.5%	
		Inverters	11.8%	
		Motors	13.5%	
		Gearbox	6.8%	
	Friction Brakes		2.8%	
Cont	Tyre Rolling Resistance		31.9%	
0	Auxliary		8.3%	

### Powertrain efficiency based on WLTC cycle

	Front	Rear
Motor	92.0%	91.0%
Inverter	96.0%	95.0%
Gearbox	97.6%	97.5%

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### **CORRELATION AND VALIDATION OF SIMULATIONS**

Increased variables and complexity

# COMPONENT LEVEL

- Battery
- Motor & Inverter
- Gearbox

# SYSTEM LEVEL

- Front and/or Rear Axle
- Controlled operating conditions
- Controlled cooling environment

## VEHICLE LEVEL

21 M V C

- Full system integration with all control systems
- Variable operating conditions
- Driver in the loop
- Limited control

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#### SIMVC

For any additional information you might need, feel free to contact me.



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